

DIAGONALIZATION OF SYMMETRIC MATRIX BY JACOBY'S METHOD

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Aim: To diagonalize a given real symmetric matrix $[A_0]$ by Jacoby's Method

What is Diagonalization?

$$[A_0] = \begin{bmatrix} \mathbf{a}_{11} & \mathbf{a}_{12} & \mathbf{a}_{13} \\ \mathbf{a}_{21} & \mathbf{a}_{21} & \mathbf{a}_{23} \\ \mathbf{a}_{31} & \mathbf{a}_{32} & \mathbf{a}_{33} \end{bmatrix} = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix} = \begin{bmatrix} 1.96 & 0 & 0 \\ 0 & 0.57 & 0 \\ 0 & 0 & 3.317 \end{bmatrix}$$

Procedure:

- 1. Select the largest (in absolute value) off diagonal element of matrix $[A_0]$ which is to be eliminated (say a_{ij})
- 2. Find the value of rotation angle θ using the expression,

3.
$$tan\theta = \frac{\pm 2 a_{ij}}{|a_{ii} - a_{jj}| + \sqrt{(a_{ii} - a_{jj})^2 + 4 a_{ij}}}$$

Plus sign is used when $a_{ii} \geq a_{jj}$ and minus sign is used when $a_{ii} \leq a_{jj}$. Also $\frac{\pi}{2} \geq \theta \geq \frac{\pi}{2}$

- 4. Prepare the transformation matrix [T] in which, $a_{ij} = -\sin\theta$; $a_{ji} = \sin\theta$; $a_{ii} = \cos\theta$;
- $a_{jj} = \cos \theta$ remaining diagonal element is 1 and rest of the elements are 0.
- 5. Find transpose of the transformation matrix $[T]^T$.
- 6. Find new matrix given by $[A_1] = [T]^T [A_0] [T]$.
- 7. Repeat the procedure from step 1 to 5 unless all off diagonal elements are eliminated.

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Diagonalization of symmetric matrix by Jacoby's Method

Example:
$$[A_0] = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{21} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

- 1. Select the largest (in absolute value) off diagonal element of matrix $[A_0]$ which is to be eliminated (say $a_{ij} = a_{23} = |-1| = 1$, which we want to eliminate).
- 2. Find the value of rotation angle θ using the expression,

We have,
$$a_{23} = 1$$
; $a_{22} = 2$; and $a_{33} = 2$

$$tan\theta = \frac{\pm 2 a_{ij}}{\left|a_{ii} - a_{jj}\right| + \sqrt{\left(a_{ii} - a_{jj}\right)^2 + 4 a_{ij}}} = \frac{\pm 2 (1)}{\left|2 - 2\right| + \sqrt{(2 - 2)^2 + 4 (1)}} = 1$$

Hence,
$$\theta = \frac{\pi}{4} = 45^{\circ}$$
; $\sin \theta = \sin \frac{\pi}{4} = 0.7071$ and $\cos \theta = \cos \frac{\pi}{4} = 0.7071$

Plus sign is used when $a_{ii} \geq a_{jj}$ and minus sign is used when $a_{ii} \leq a_{jj}$. Also $\frac{\pi}{2} \geq \theta \geq \frac{\pi}{2}$

1. Prepare the transformation matrix [T] in which,

$$a_{23} = -sin\,\theta = -0.7071$$
 ; $a_{32} = sin\,\theta = 0.7071$;

$$a_{22} = \cos \theta = 0.7071$$
; $a_{33} = \cos \theta = 0.7071$

and remaining diagonal element is 1 and rest of the elements are 0.

$$[T] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos\theta & -\sin\theta \\ 0 & \sin\theta & \cos\theta \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0.7071 & -0.7071 \\ 0 & 0.7071 & 0.7071 \end{bmatrix}$$

Find transpose of the transformation matrix $[T]^T$

$$[T]^T = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0.7071 & 0.7071 \\ 0 & -0.7071 & 0.7071 \end{bmatrix}$$

Find new matrix given by $[A_1] = [T]^T [A_0] [T]$

$$[A_1] = [T]^T [A_0] [T] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0.7071 & 0.7071 \\ 0 & -0.7071 & 0.7071 \end{bmatrix} \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0.7071 & -0.7071 \\ 0 & 0.7071 & 0.7071 \end{bmatrix}$$

$$[A_1] = \begin{bmatrix} 2 & -0.7071 & 0.7071 \\ -0.7071 & 0.999 & \mathbf{0} \\ 0.7071 & \mathbf{0} & 2.999 \end{bmatrix}$$

$$[A_1] = \begin{bmatrix} 2 & -0.7071 & 0.7071 \\ -0.7071 & 0.999 & 0 \\ 0.7071 & 0 & 2.999 \end{bmatrix}$$

Select the largest (in absolute value) off diagonal element of matrix $[A_0]$ which is to be eliminated

(say $a_{ij} = a_{31} = 0.7071$, which we want to eliminate).

Find the value of rotation angle θ using the expression,

We have, $a_{33} = 3$; $a_{22} = 2$; and $a_{31} = 0.7071$

$$tan\theta = \frac{\pm 2 a_{ij}}{\left|a_{ii} - a_{jj}\right| + \sqrt{\left(a_{ii} - a_{jj}\right)^2 + 4 a_{ij}}} = \frac{\pm 2 (0.7071)}{\left|3 - 2\right| + \sqrt{(3 - 2)^2 + 4 (0.7071)}} = 0.478$$

Hence, $\theta = 25^{\circ} 33'$; $\sin \theta = \sin 25^{\circ} 33' = 0.4312$ and $\cos \theta = \cos 25^{\circ} 33' = 0.9022$

$$[A_2] = [T]^T [A_1] [T] = \begin{bmatrix} 0.902 & 0 & -0.431 \\ 0 & 1 & 0 \\ 0.431 & 0 & 0.902 \end{bmatrix} \begin{bmatrix} 2 & -0.707 & 0.707 \\ -0.707 & 0.999 & 0 \\ 0.707 & 0 & 2.999 \end{bmatrix} \begin{bmatrix} 0.902 & 0 & 0.431 \\ 0 & 1 & 0 \\ -0.431 & 0 & 0.902 \end{bmatrix}$$

$$[A_2] = \begin{bmatrix} 1.63 & -0.63 & \mathbf{0} \\ -0.63 & 1 & -0.30 \\ \mathbf{0} & -0.30 & 3.36 \end{bmatrix}$$

$$[A_2] = \begin{bmatrix} 1.63 & -0.63 & \mathbf{0} \\ -0.63 & 1 & -0.30 \\ \mathbf{0} & -0.30 & 3.36 \end{bmatrix}$$

Select the largest (in absolute value) off diagonal element of matrix $[A_0]$ which is to be eliminated (say $a_{ij} = a_{21} = 0.63$, which we want to eliminate).

Find the value of rotation angle θ using the expression,

We have,
$$a_{22} = 1$$
; $a_{11} = 1.63$; and $a_{21} = 0.63$

$$tan\theta = \frac{\pm 2 a_{ij}}{\left|a_{ii} - a_{jj}\right| + \sqrt{\left(a_{ii} - a_{jj}\right)^2 + 4 a_{ij}}} = \frac{\pm 2 (0.63)}{\left|0.63\right| + \sqrt{(0.63)^2 + 4 (0.63)}} = 0.5384$$

Hence, $\theta = 28^{\circ} 17'$; $\sin \theta = \sin 28^{\circ} 17' = 0.4738$ and $\cos \theta = \cos 28^{\circ} 17' = 0.8806$

$$[A_3] = [T]^T [A_2] [T] = \begin{bmatrix} 0.880 & -0.473 & 0 \\ 0.473 & 0.880 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1.63 & -0.63 & 0 \\ -0.63 & 1 & -0.30 \\ 0 & -0.30 & 3.36 \end{bmatrix} \begin{bmatrix} 0.880 & 0.473 & 0 \\ -0.473 & 0.880 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$[A_3] = \begin{bmatrix} 2 & \mathbf{0} & 0.14 \\ \mathbf{0} & 0.61 & -0.26 \\ 0.14 & -0.26 & 3.36 \end{bmatrix}$$

$$[A_3] = \begin{bmatrix} 2 & 0 & 0.14 \\ 0 & 0.61 & -0.26 \\ 0.14 & -0.26 & 3.36 \end{bmatrix}$$

Select the largest (in absolute value) off diagonal element of matrix $[A_0]$ which is to be eliminated (say $a_{ij} = a_{32} = 0.26$, which we want to eliminate).

Find the value of rotation angle θ using the expression,

We have, $a_{33} = 3.36$; $a_{22} = 0.61$; and $a_{32} = 0.26$

$$tan\theta = \frac{\pm 2 a_{ij}}{\left|a_{ii} - a_{jj}\right| + \sqrt{\left(a_{ii} - a_{jj}\right)^2 + 4 a_{ij}}} = \frac{\pm 2 (0.26)}{\left|2.75\right| + \sqrt{(2.75)^2 + 4 (0.26)}} = 0.0915$$

Hence, $\theta = 5^{\circ} 13'$; $\sin \theta = \sin 5^{\circ} 13' = 0.090$ and $\cos \theta = \cos 5^{\circ} 13' = 0.995$

$$[A_4] = [T]^T [A_3] [T] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0.995 & 0.090 \\ 0 & -0.090 & 0.995 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0.14 \\ 0 & 0.61 & -0.26 \\ 0.14 & -0.26 & 3.36 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0.995 & -0.090 \\ 0 & 0.090 & 0.995 \end{bmatrix}$$

$$[A_4] = \begin{bmatrix} 2 & 0 & 0.138 \\ 0 & 0.578 & 0 \\ 0.138 & 0 & 3.34 \end{bmatrix}$$

$$[A_4] = \begin{bmatrix} 2 & 0 & 0.138 \\ 0 & 0.578 & 0 \\ 0.138 & 0 & 3.34 \end{bmatrix}$$

Select the largest (in absolute value) off diagonal element of matrix $[A_0]$ which is to be eliminated

(say $a_{ij} = a_{31} = 0.138$, which we want to eliminate).

Find the value of rotation angle θ using the expression,

We have, $a_{33} = 3.34$; $a_{11} = 2$; and $a_{31} = 0.138$

$$tan\theta = \frac{\pm 2 a_{ij}}{\left|a_{ii} - a_{jj}\right| + \sqrt{\left(a_{ii} - a_{jj}\right)^2 + 4 a_{ij}}} = \frac{\pm 2 (0.138)}{\left|1.34\right| + \sqrt{(1.34)^2 + 4 (0.138)}} = 0.096$$

Hence, $\theta = 5^{\circ} 29'$; $\sin \theta = \sin 5^{\circ} 29' = 0.095$ and $\cos \theta = \cos 5^{\circ} 29' = 0.992$

$$[A_5] = [T]^T [A_4] [T] = \begin{bmatrix} 0.992 & 0 & -0.095 \\ 0 & 1 & 0 \\ 0.095 & 0 & 0.992 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0.138 \\ 0 & 0.578 & 0 \\ 0.138 & 0 & 3.34 \end{bmatrix} \begin{bmatrix} 0.992 & 0 & 0.095 \\ 0 & 1 & 0 \\ -0.095 & 0 & 0.992 \end{bmatrix}$$

$$[A_5] = \begin{bmatrix} 1.96 & 0 & 0 \\ 0 & 0.57 & 0 \\ 0 & 0 & 3.317 \end{bmatrix}$$

Some Examples

$$[A_0] = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix} = \begin{bmatrix} 1.96 & 0 & 0 \\ 0 & 0.57 & 0 \\ 0 & 0 & 3.317 \end{bmatrix}$$

$$[A_0] = \begin{bmatrix} 3 & -1 & 0 \\ -1 & 3 & -1 \\ 0 & -1 & 3 \end{bmatrix} = \begin{bmatrix} 3.00 & 0 & 0 \\ 0 & 1.585 & 0 \\ 0 & 0 & 4.414 \end{bmatrix}$$

$$[A_0] = \begin{bmatrix} 1 & 2 & 1 \\ 6 & -1 & 0 \\ -1 & -2 & -1 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & -4 \end{bmatrix}$$

$$[A_0] = \begin{bmatrix} 2 & 0 & 1 \\ 0 & 2 & 0 \\ 1 & 0 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

$$[A_0] = \begin{bmatrix} 3 & 0 & 1 \\ 0 & 3 & 0 \\ 1 & 0 & 3 \end{bmatrix} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

$$[A_0] = \begin{bmatrix} 3 & 0 & 2 \\ 0 & 3 & 0 \\ 2 & 0 & 3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{bmatrix}$$

$$[A_0] = \begin{bmatrix} 2 & 0 & 2 \\ 0 & 2 & 0 \\ 2 & 0 & 2 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

$$[A_0] = \begin{bmatrix} 2 & 0 & 3 \\ 0 & 2 & 0 \\ 3 & 0 & 2 \end{bmatrix} = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 5 \end{bmatrix}$$